

Towards Real Time Radiotherapy Simulation

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Outline

- Problem Description
- Programming Model
- Architecture
- Evaluation
- Conclusions and Future Work

Problem Description

- Radiotherapy common treatment for cancer
 - Idea: Kill cancer using high radioactive dose
 - It is important to limit damage of healthy tissue
- Monte Carlo Simulations are used as common tool for dose simulation
 - Need to simulate huge number of particles to achieve statistical meaningful results
 - Computationally expensive / long runtimes

Performance Target



- Dose simulation at real time
 - Simulate representative dose in less than 1 sec
 - Requires simulation of 100 million particles
- This will enable adaptive treatment
 - New state of the art machines combine MRI scanning with linear accelerator
 - In most cases the cancerous organ moves within the body between CT and therapy
 - Or even during the therapy session
 - -> Less sessions required, more targeted treatments with less damage to the healthy tissue

Monte Carlo Dose Simulation

- Patient body data represented as cube
 - Cube is discretised in voxels
- Particles are sent into the cube
 - Each particle has energy and fuel values, determining travel distance as well as a direction vector
 - When fuel runs out
 - particle interaction of a certain kind is selected
 - the voxel dose is aggregated
 - a new particle direction is randomly set
 - When energy runs out the particle gets absorbed / removed

FPGA Implementation Challenges

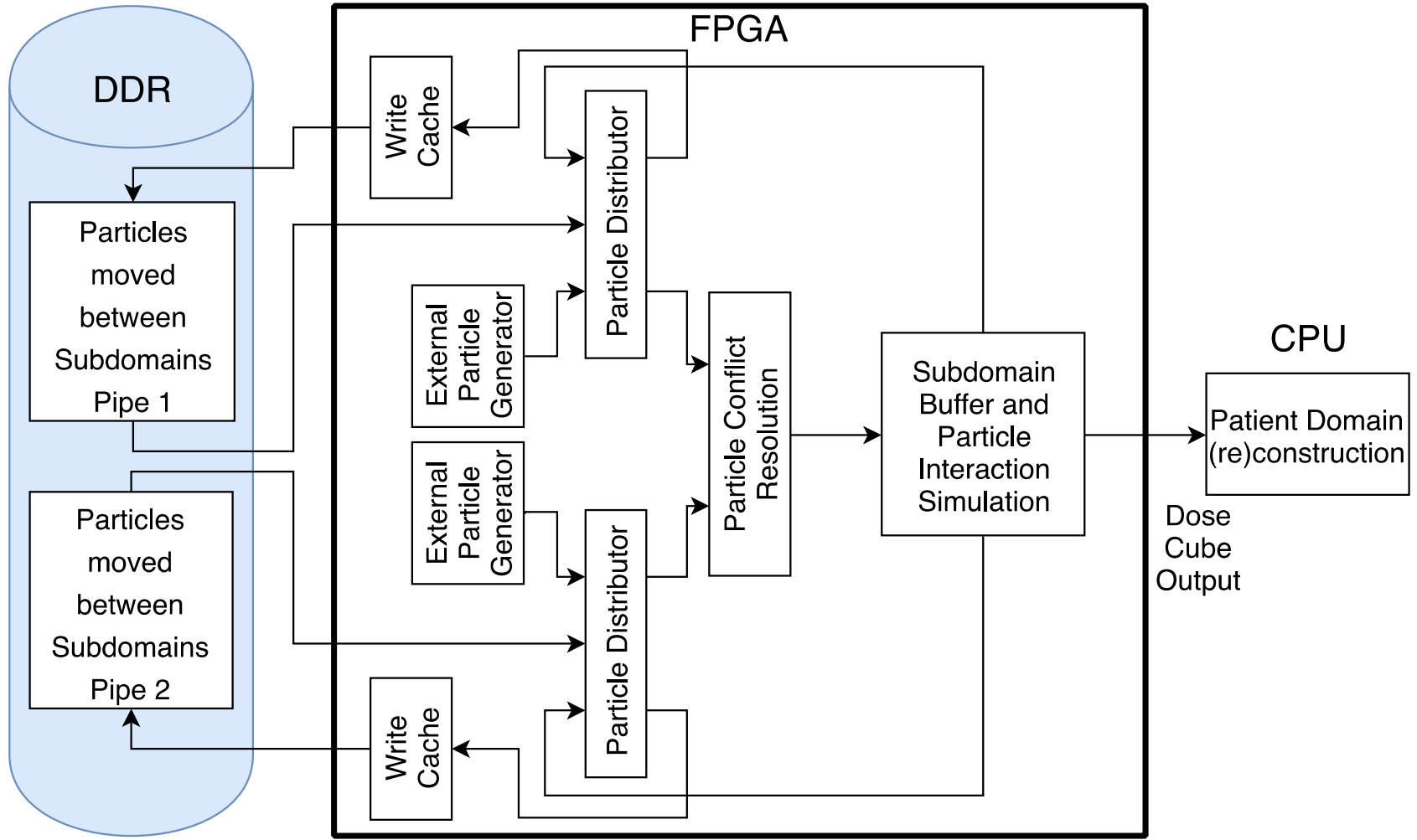
- The path through the patient cube is random
- Patient cube size is much bigger than FPGA on-chip memory
 - -> Decompose big cube into smaller sub domains
- Particles are processed in a loop
 - Final result is needed to start next loop iteration
 - Direct data dependency between loop iterations interferes with pipelined execution
 - -> Reorder compute to process only one iteration per particle incrementally, to break dependency

Programming Model: Dataflow

- Describe your computation as a directed graph
- Data flows through the graph, and gets processed while traversing through the nodes
- Maxeler's MaxCompiler tool chain maps onto dataflow engines (DFEs)
- Current generation DFE: MAX5C
 - based on VU9P FPGA from Xilinx
 - ~7,000 multipliers
 - ~40 MB on chip memory
 - 48 GB DDR4 memory
 - ~50 GB/s memory bandwidth



Our Architecture



Evaluation

- Targeting Maxeler MAX5C DFEs using MaxCompiler 2018.3.1 and Vivado 2018.2
- CPU platform 2x Xeon E5-2643 v4 (6 cores each @ 3,4 GHz)

Frequency	Design Count	Kernel Parallelism	Cube Size	Subdomain Size	LUT	FF	DSP	BRAM	URAM
250	3	2	128	64	543,642 (45.98%)	1,069,421 (45.23%)	2,457 (35.92%)	2,916 (67.5%)	384 (40%)

Cards	FPGA Time [ms]	Total Time [ms]
1	3,267	3,435
2	1,173	1,342
3	810	988

- 4.1x speedup compared to CPU
- 8x speedup compared to GPU
 - Due to random memory access and different interactions problem with SIMD execution

Conclusion and Future Work

- Conclusions
 - Presented architecture for FPGA based Monte Carlo radiotherapy simulation
 - Detailed performance model (in the paper)
 - Met real time requirement of simulating 100 million particles in less than one second using three FPGA cards
 - 4x speedup over CPU and 8x over GPU
- Future Work
 - Implement additional particle interaction (bremsstrahlung)
 - More particle types and materials
 - Integration into latest radiotherapy systems

Questions?



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